

[gla:na] East Gothian: Stare

#### Hyperspectral imaging using a continuous variable bandpass filter

Jörgen Ahlberg<sup>1,2</sup> Ingmar Renhorn<sup>1</sup>

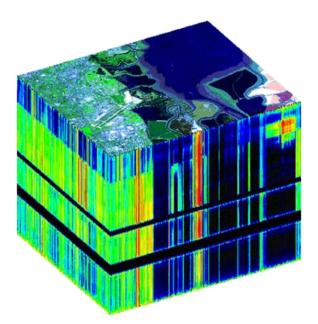
1 Glana Sensors AB, Sweden. www.glana.se 2 Computer Vision Laboratory, Linköping University, Sweden

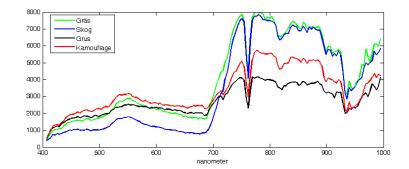


# What?

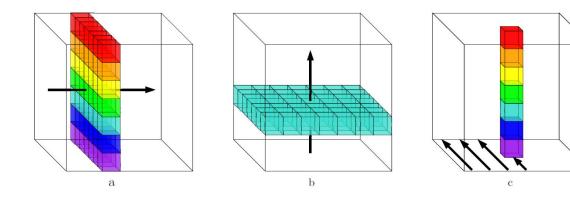


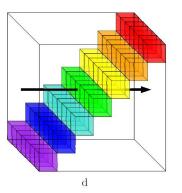
#### Hyperspectral data

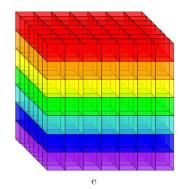


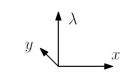


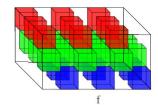










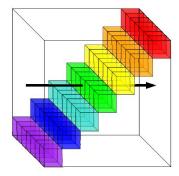


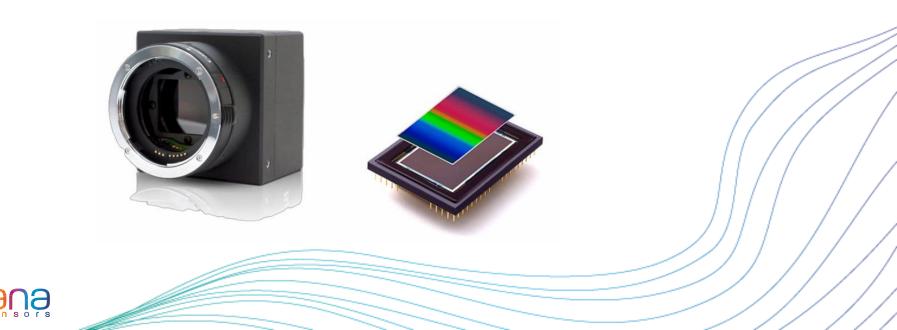


# How?

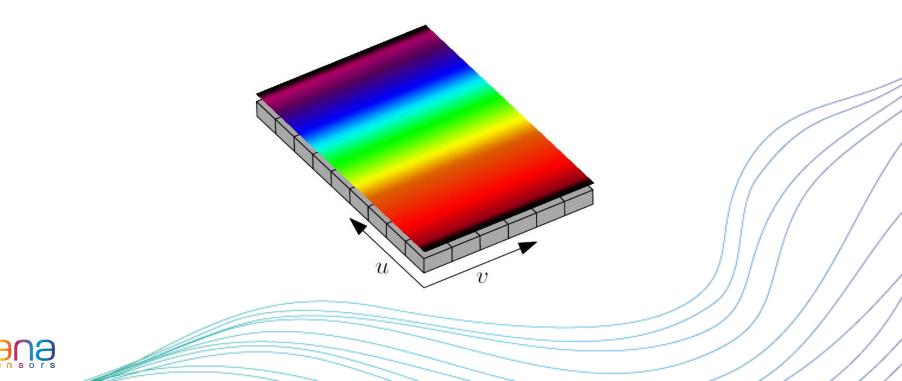


### The Glana camera

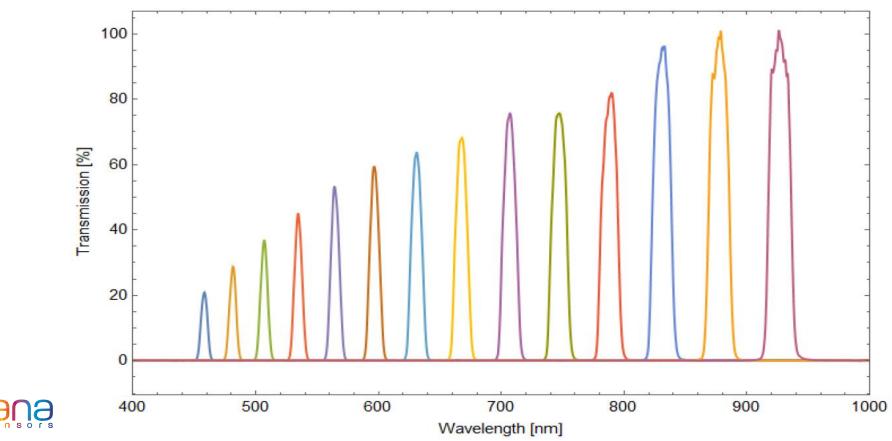


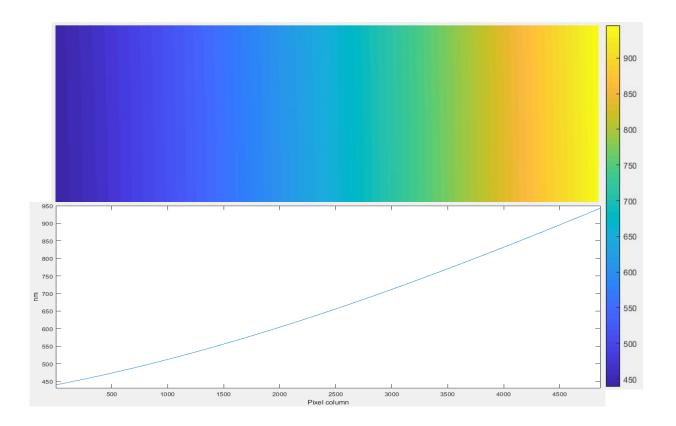


#### Key component: Continuously varying band-pass filter

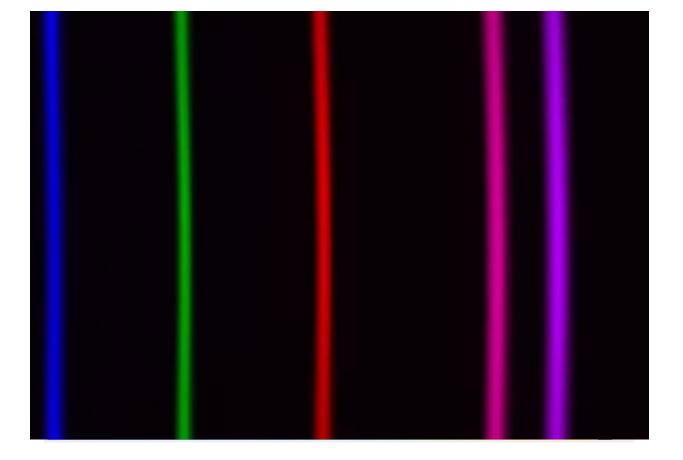


#### The filter



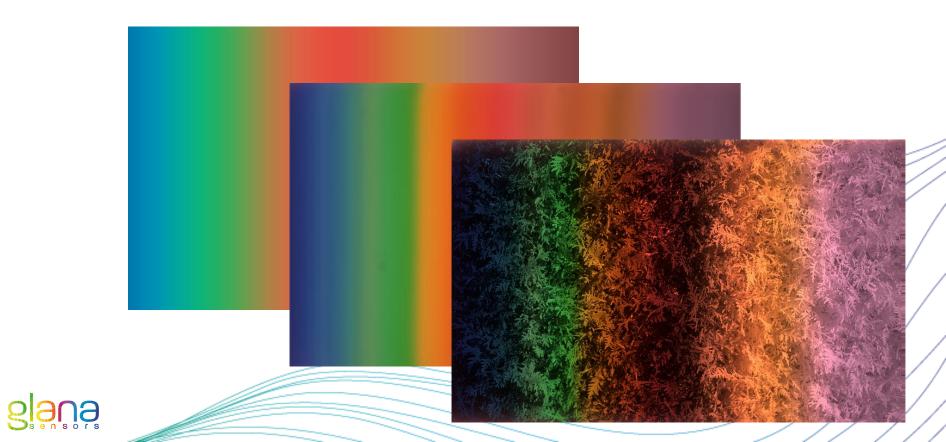






<u>Slaus</u>

$$\begin{split} \lambda_{Canon90}(nr,nc) &= 441.74 + 0.061945\,nc + 0.0000113116\,nc^2 - 5.63836\,10^{-10}\,nc^3 \\ &- 0.00280829\,nr - 1.15454\,10^{-7}\,nc\,nr + 7.45792\,10^{-7}\,nr^2 \end{split}$$







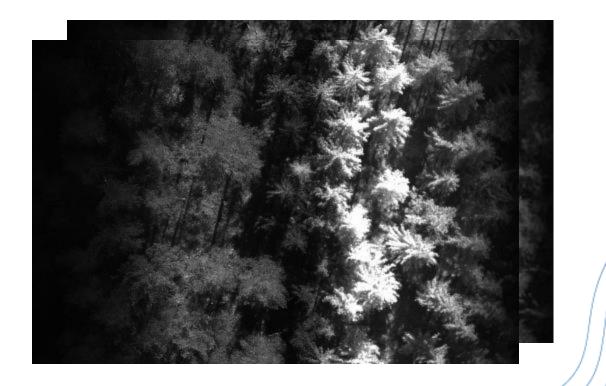
#### Why?

- We can register and reconstruct 3D.
- We get very high spatial resolution.
- We get enough spectral resolution for many applications.
- Area coverage.





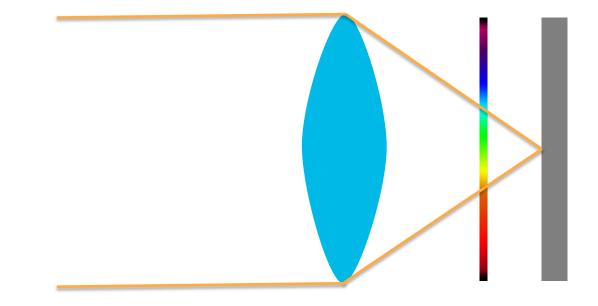




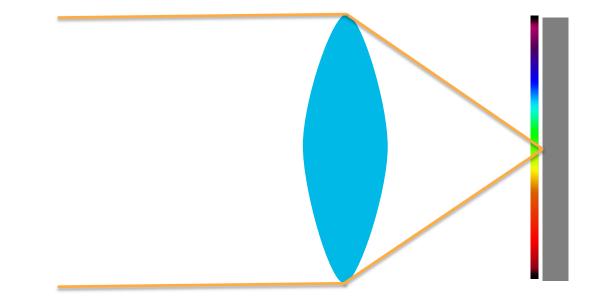




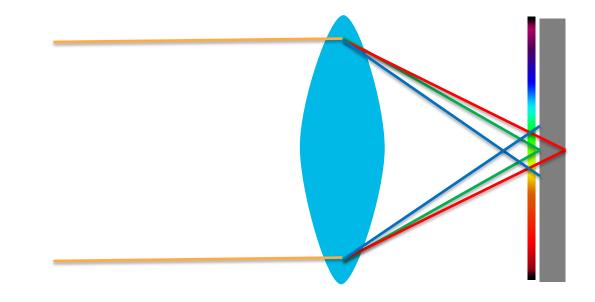




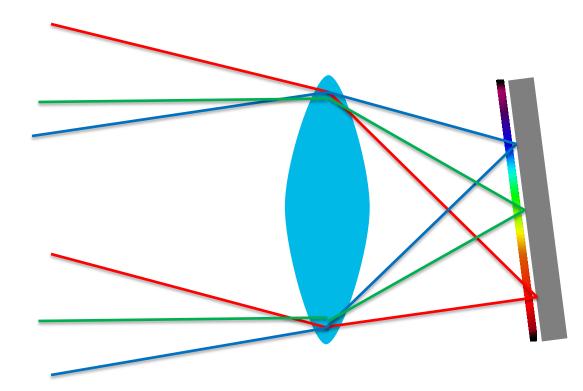




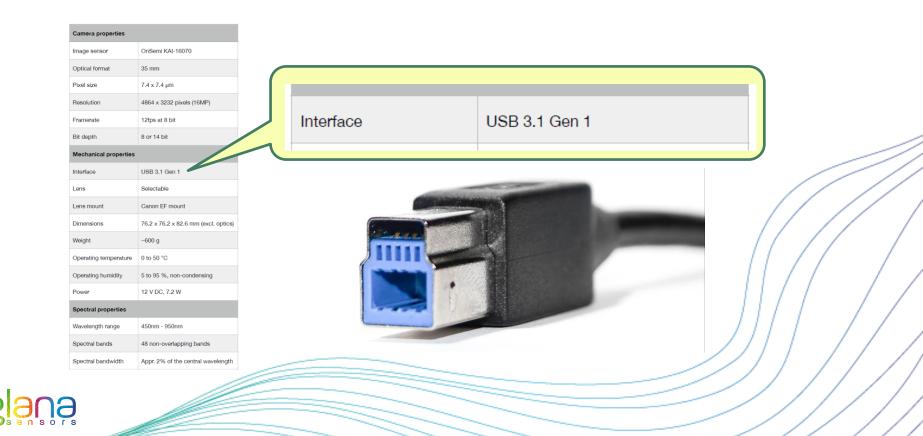




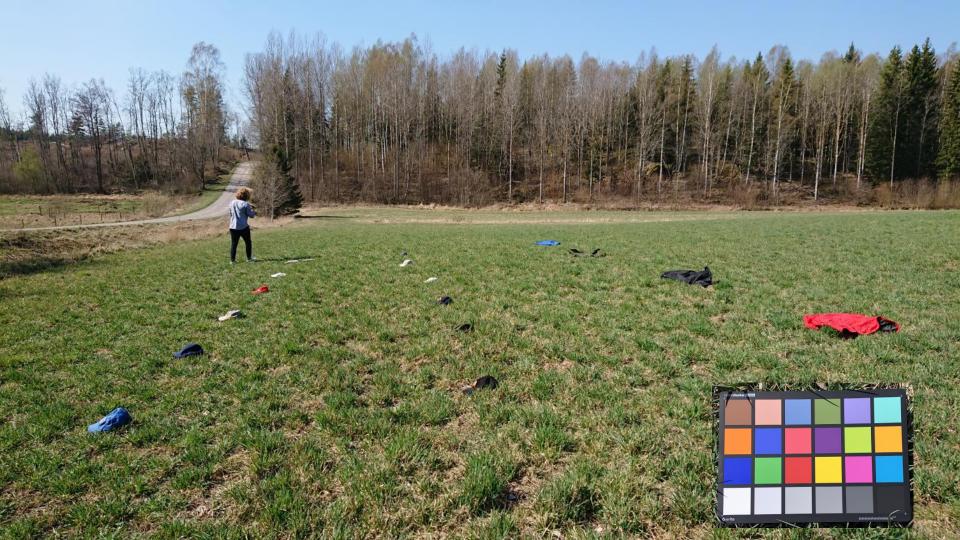


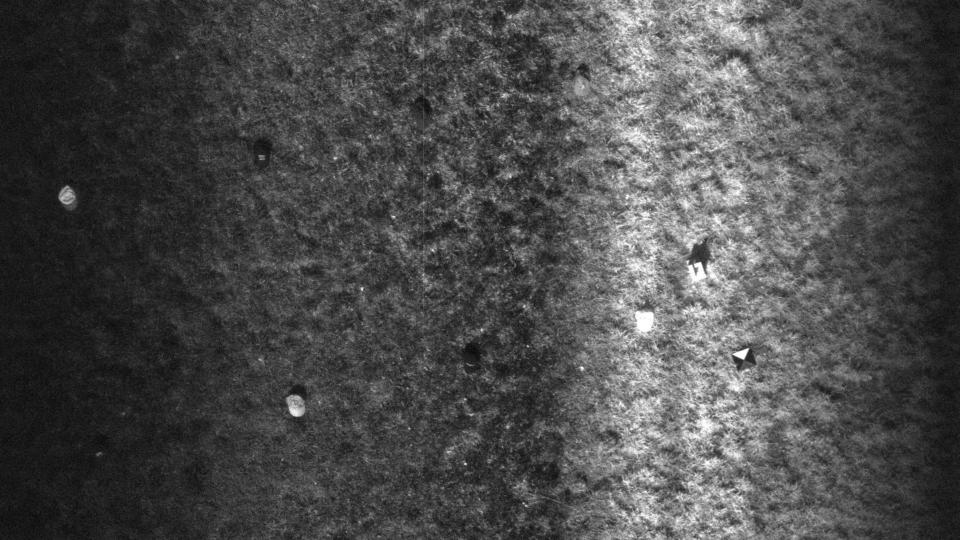












# Airport



## 3D Reconstruction of Västervik

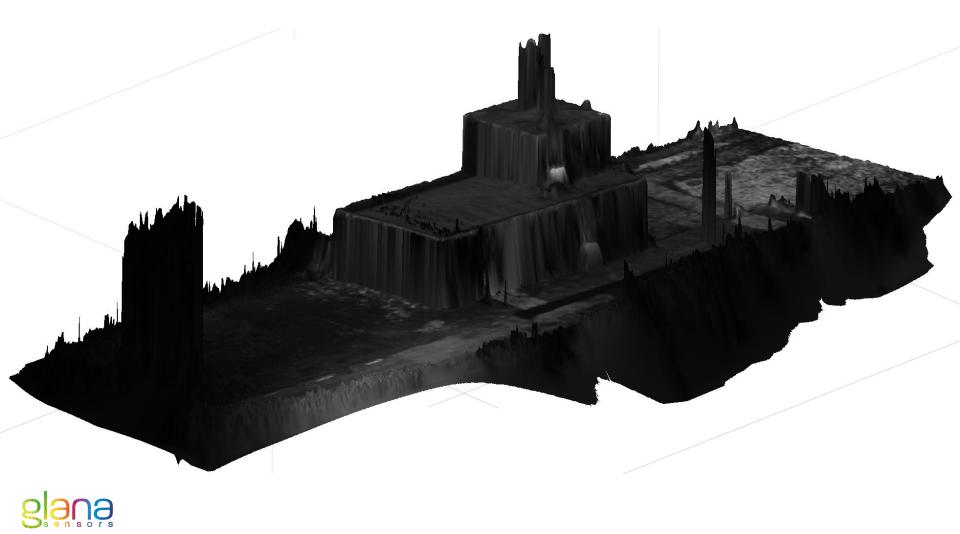
not so

## International Airport





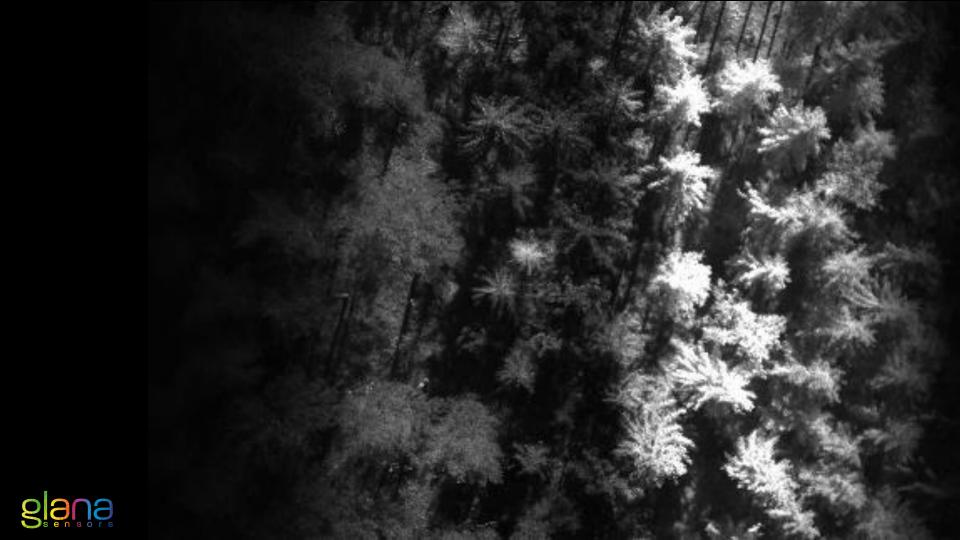




## Forest

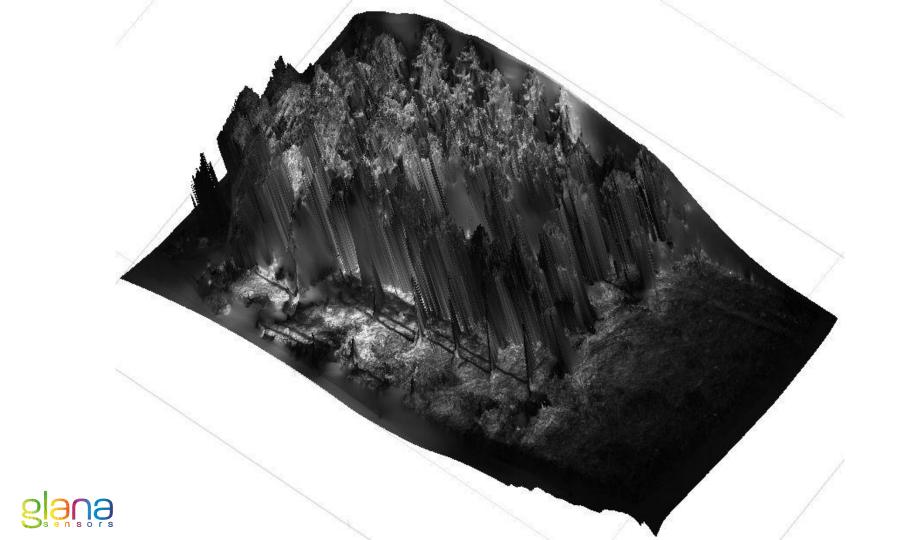


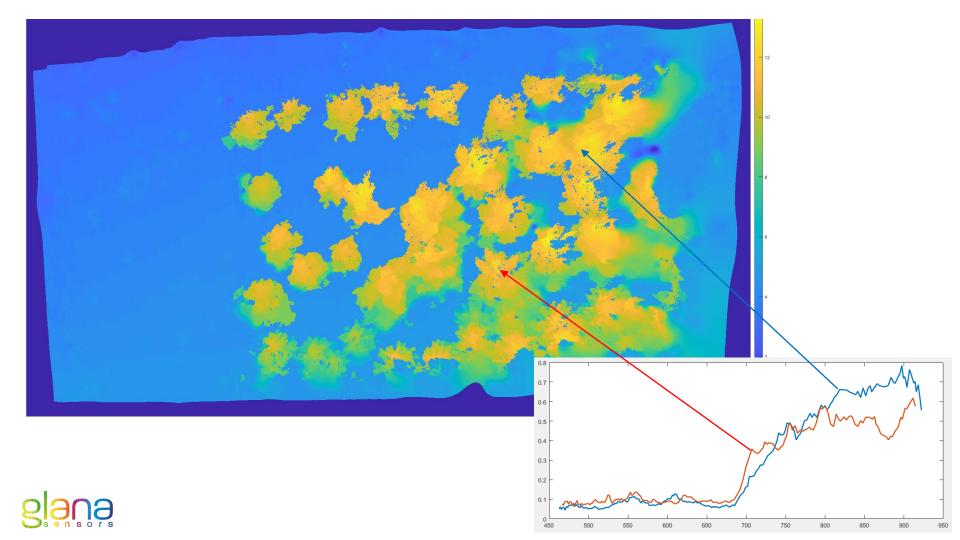












# And now?



#### Status & Progress

- A lot of practicalities to solve, with almost no manpower
- Rely heavily on partners (FOI, RMA, RISE, TST)
- · We do have the entire processing chain, but still a lot of hacks
- Analysis of camoflage spectra: RMA will present
- Registration of spatio-spectral data: FOI will present

